Inductive-Recursive Definitions

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- 1. Dependent Type Theory.
- 2. Sets in Martin-Löf Type Theory and Principles of Ind.-Rec.
- 3. Closed Formalisation of Induction-Recursion.
- 4. Results.

Goal of this Talk

- Define an extension of Martin-Löf Type Theory (MLTT) which allows to define all types definable in standard extensions of MLTT without any encoding.
- Gives rise to a proof theoretically very strong extension of positive inductive definitions.
- New principle where we define

 $T: U \to Set$

in such a way that the domain $\rm U$ of $\rm T$ depends on $\rm T.$

New Grant

Induction-Recursion topic of an EPSRC grant involving Neil Ghani, Peter Hancock (Glasgow Strathclyde), Thorsten Altenkirch (Nottingham) and A. S. (Swansea).

1. Dep. Type Theory

- Dependent type theory (version used here: Martin-Löf Type Theory) is functional programming based on dependent types.
- Set will in the following denote a "small type".
- Most types used in ordinary programming languages are simple types (no dependencies):
 - String : Set,
 - Integer : Set,
 - Integer \rightarrow Integer : Set,
 - etc.

Polymorphic Types

Polymorphic types ("generics") allow types to depend on other types.

● E.g.

```
\mathrm{List}:\mathrm{Set}\to\mathrm{Set}\ ,
```

List(A) = set of lists of elements of set A.

- Polymorphic types allow more generic programs.
 - \checkmark One definition of a library for ${\rm List}$
 - rather than defining this library for each of
 - List(Integer),

 - List(String),

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Dependent Types

- Dependent types allow types to depend on other types and elements of other types.
 - Simple examples:
 - The set of n-tuples of elements of A is

 $\operatorname{Tuple}(A, n)$

where

Tuple : Set $\rightarrow \mathbb{N} \rightarrow Set$

Allows to define functions, the result type of which depends on the argument, e.g.

$$f:(n:\mathbb{N})\to\operatorname{Tuple}(\mathbb{N},n)$$

Examples of Dependent Types

• The set of $n \times m$ -matrices (of some fixed set) is

Mat(n,m)

where

 $\mathrm{Mat}:\mathbb{N}\to\mathbb{N}\to\mathrm{Set}$

Matrix multiplication gets type

matmult : $(n, m, k : \mathbb{N})$ $\rightarrow \operatorname{Mat}(n, m) \rightarrow \operatorname{Mat}(m, k) \rightarrow \operatorname{Mat}(n, k)$

Predicates as Dependent Types

The predicate

Sorted : $\text{List}(\mathbb{N}) \to \text{Set}$

s.t. there exists p : Sorted(l) iff l is sorted is a dependent type.

• The set $(l : \text{List}(\mathbb{N})) \times \text{Sorted}(l)$ is the set of sorted lists.

The set

 $(l : \operatorname{List}(\mathbb{N})) \to (l' : \operatorname{List}(\mathbb{N})) \times \operatorname{Sorted}(l') \times (\operatorname{EqElements}(l, l'))$

is the set of sorting functions on $\operatorname{List}(\mathbb{N})$.

Logical Framework

- Basic logic framework has 2 main constructions:
- The dependent function type $(x : A) \rightarrow B(x)$ for A : Set, $x : A \Rightarrow B(x) : Set$.
 - Elements are roughly speaking

$$\{f: A \to \bigcup_{x:A} B(x) \mid \forall x \in A. f(x) \in B(x)\}$$

- $A \to B$ is the special case $(x : A) \to B$ where B does not depend on x.
- The dependent product $(x : A) \times B(x)$ for A : Set, $x : A \Rightarrow B : Set$.
 - Elements are roughly speaking

 $\{\langle a, b \rangle \mid a \in A, b \in B(a)\}$

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Set vs. Type

- We will use two type levels.
 - Set, the type of sets = small types.
 - Type the collection of big types.
 - Set \subseteq Type, Set : Type.
 - Type closed under (dependent) functions and products, but in the simplest version under nothing else.
 - So we have for instance, if A : Set, then

$$A \rightarrow \text{Set} : \text{Type}$$

type of predicates over A.

Higher hierarchies are considered.
 Universes provide a much more powerful type hierarchy.

2. Sets in MLTT and Ind.-Rec.

- Simples type = type of Booleans.
- **•** Formation rule:

 $\operatorname{Bool}:\operatorname{Set}$

Introduction rules:

tt : Bool ff : Bool

Elimination/equality rules:

If then else.

Visualisation of Bool



2 Constructors, both no arguments.

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The Disjoint Union

Formation rule:

$$\frac{A:\operatorname{Set} \quad B:\operatorname{Set}}{A+B:\operatorname{Set}}$$

Introduction rules:

$$inl: A \to (A+B)$$
$$inr: B \to (A+B)$$

(Additional premises of formation rule suppressed).

• Elimination/equality rule:

case x of

$$\{ inl(a) \rightarrow \cdots$$

 $inr(b) \rightarrow \cdots \}$

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Visualisation of A+B



• Both inl and inr have one non-inductive argument.

The Σ -Type

Formation rule:

$$\frac{A: \text{Set} \quad B: A \to \text{Set}}{\Sigma(A, B): \text{Set}}$$

Introduction rule:

$$\begin{array}{cc} a:A & b:B(a) \\ \hline \mathbf{p}(a,b):\Sigma(A,B) \end{array}$$

Elimination/equality rule:

case x of

$$\{ p(a,b) \rightarrow \cdots \}$$

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Visualisation of Σ (A,B)



- p has 2 non-inductive arguments.
- The type of the 2nd argument depends on the 1st argument.

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Natural numbers

Formation rule:

 $\mathbb{N}: \mathrm{Set}$

Introduction rules:

$$O:\mathbb{N}$$
 $\frac{n:\mathbb{N}}{\mathrm{S}(n):\mathbb{N}}$

Elimination/equality rule:

Induction/primitive recursion.

Visualisation of \mathbb{N}



- 0 has no arguments.
- **•** S has one **inductive argument**.

W-Type



Assume $A : Set, B : A \to Set$. W(A, B) is the type of well-founded recursive trees with branching degrees $(B(a))_{a:A}$.

The W-Type

Formation rule:

$$\frac{A: \text{Set} \quad B: A \to \text{Set}}{W(A, B): \text{Set}}$$

Introduction rule:

$$a: A \qquad b: B(a) \to W(A, B)$$

 $\sup(a, b): W(A, B)$

Elimination/equality rule:

Induction over trees.

Visualisation of W(A,B)



sup has 2 arguments:

- First argument is non-inductive.
- **Second argument is inductive**, indexed over B(a).

• B(a) depends on the first argument a.

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Universes

- A universe is a family of sets
- Given by
 - \checkmark a set $\mathrm{U}:\mathrm{Set}$ of codes for sets,
 - \checkmark a decoding function $T:U \rightarrow Set.$

Universes

Formation rules:

$$U: Set \qquad \frac{a:U}{T(a):}$$

Set

Introduction and Equality rules:

$$\widehat{\mathbb{N}} : \mathbf{U} \qquad \mathbf{T}(\widehat{\mathbb{N}}) = \mathbb{N}$$
$$\frac{a: \mathbf{U} \qquad b: \mathbf{T}(a) \to \mathbf{U}}{\widehat{\Sigma}(a, b): \mathbf{U}}$$
$$\mathbf{T}(\widehat{\Sigma}(a, b)) = \Sigma(\mathbf{T}(a), \mathbf{T} \circ b)$$

Similarly for other type formers (except for ${\rm U}$).

Elimination/equality rules: Induction over U.

Visualisation of U



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Analysis

- Elements of U are defined inductively, while defining T(a) for a : U recursively.
- **9** $\widehat{\Sigma}$ has two **inductive arguments**
 - Second argument depends on T(a).
 - T(a) depends on T applied to first argument a.
 - $T(\widehat{\Sigma}(a,b))$ is defined from
 - T(a).
 - T(b(x)) (x : T(a)).
- Principles for defining a universe can be generalised to higher type universes, where T(a) can be an element of any type, e.g. Set → Set.

Advanced Example

- Set of lists of natural numbers with distinct elements.
- Inductive-recursive definition of
 - \bullet Freshlist : Set
 - $_\#$: Freshlist $\rightarrow \mathbb{N} \rightarrow \text{Set.}$
- Constructors:

nil : Freshlist , nil # $m = \top$

cons : $(n : \mathbb{N}, l : \text{Freshlist}, l \# n) \to \text{Freshlist}$ $\cos(n, l, p) \# m = (l \# m) \land (n \neq m)$

3. Closed Formal. of Induct-Rec.

- The above constructions are examples of inductive-recursive definitions.
 - Many more sets can be defined in the same way.
- Inductive-recursive Definitions = general concepts which subsumes most standard extensions which have been found up to now.
 - Excludes Mahlo universe and similar constructions.
- Introduced originally by Peter Dybjer in a schematic way.
- Here: development of a rule based system, which allows to introduce all ind.-rec. def. by finitely many rule schemes.

Encoding of Constructors into one

- Several constructors can be encoded into one constructor:
 - Assume constructors $C_i : (a : A_i) \rightarrow U$ (i = 1, ..., n).
 - Replace them by one constructor $C: (i: \{1, \ldots, n\}, a: A_i) \rightarrow U.$
- Only required: finite sets.
 Will be part of the logical framework.

Induct. and Non-Induct. Arguments

- **•** Two kinds of arguments:
 - Non-inductive arguments.
 - Refer to sets previously introduced.
 - Inductive arguments.
 - Refer to the set to be defined ind.-rec.
 - Additional initial case: constructors with no arguments.

Depend. of Args. on Prev. Ones

- Types of later arguments can depend directly on previous non-inductive arguments.
- Later arguments cannot depend directly on inductive arguments (since nothing is known about the ind.-rec. introduced set U).
 - However, they can depend on T applied to inductive arguments.
- Result of T applied to the constructed element can depend in the same way on arguments as can later arguments depend on previous arguments.

Formalisation

- We introduce inductive-recursively sets U : Set, $T : U \rightarrow D$ for some type D.
- Let D : Type be fixed.
 - In case of a standard universe

D = Set

In case of higher order universes

$$D = \operatorname{Fam}(\operatorname{Set}) \to \operatorname{Fam}(\operatorname{Set})$$

or higher types.

In case of inductive definitions (T is trivial)

$$D = \{*\}$$

OP_D

We introduce a type of codes for ind.-rec. definitions:

 OP_D : Type

If $\gamma : OP_D$, we introduce (U_{γ}, T_{γ}) ind.-rec.:

$$\begin{array}{rcl} \mathrm{U}_{\gamma} & : & \mathrm{Set} \\ \mathrm{T}_{\gamma} & : & \mathrm{U}_{\gamma} \to D \end{array}$$

$\mathbf{F}_{\gamma}^{\mathrm{U}}$

- Further, we define the set of arguments of the constructor $intro_{\gamma}$ of U_{γ} .
 - Argument set has to be defined, before ${\rm U}_{\gamma},\,{\rm T}_{\gamma}$ has been introduced.
 - Will be defined for arbitrary $U : \text{Set}, T : U \to D$ $\gamma : OP_D$

$$F_{\gamma}^{U}: (U: Set) \to (T: U \to D) \to Set$$

• Introduction Rule for U_{γ} :

$$intro_{\gamma}: F^{U}_{\gamma}(U_{\gamma}, T_{\gamma}) \to U_{\gamma}$$



- Furthermore, we have to define the result of T_{γ} applied to $intro_{\gamma}(a)$.
 - Again, we have to define it before the definition of U_{γ} , T_{γ} is finished.
- So we define

$$F_{\gamma}^{T}: (U: Set) \to (T: U \to D) \to F_{\gamma}^{U}(U, T) \to D$$

• Equality Rule for T_{γ} :

$$T_{\gamma}(\operatorname{intro}_{\gamma}(a)) = F_{\gamma}^{T}(U_{\gamma}, T_{\gamma}, a)$$



$$\begin{aligned} \mathbf{F}^{\mathbf{U}}_{\gamma} &: & (U: \operatorname{Set}) \to (\mathbf{T}: U \to D) \to \operatorname{Set} \\ \mathbf{F}^{\mathbf{T}}_{\gamma} &: & (U: \operatorname{Set}) \to (\mathbf{T}: U \to D) \to \mathbf{F}^{\mathbf{U}}_{\gamma}(U, T) \to D \end{aligned}$$

 \checkmark F_{γ}^{U} , F_{γ}^{T} will form the object part of a functor

$$F_{\gamma} : Fam(D) \to Fam(D)$$

where

$$\operatorname{Fam}(D) := (U : \operatorname{Set}) \times (U \to D)$$

and $\langle U_{\gamma}, T_{\gamma} \rangle$ is the initial algebra of F_{γ} . (Slight modification of the proof in the paper is needed.)

Elimin./Equal. Rules for U_{γ} , T_{γ}

- For elimination and equality rules similar functions F_{γ}^{IH} , F_{γ}^{map} can be defined.
- Not treated here.

Initial Case

- Initial case for OP_D : No arguments.
 - We need only to define the result of T_{γ} applied to the constructor, i.e. require one element $\psi : D$.

$$\frac{\psi:D}{\operatorname{init}(\psi):\operatorname{OP}_D}$$

$$F^{\mathrm{U}}_{\operatorname{init}(\psi)}(U,T) = \{*\}:\operatorname{Set}$$

$$F^{\mathrm{T}}_{\operatorname{init}(\psi)}(U,T,*) = \psi:D$$

Noninductive Argument

- For an noninductive argument we need to know
 - The set *A*, the argument is referring to.
 - Depending on A, the later arguments of the constructor, i.e. a function $\psi : A \to OP_D$.

$$\frac{A : \text{Set} \quad \psi : A \to \text{OP}_D}{\text{nonind}(A, \psi) : \text{OP}_D}$$
$$F^{\text{U}}_{\text{nonind}(A, \psi)}(U, T) = (a : A) \times F^{\text{U}}_{\psi(a)}(U, T) : \text{Set}$$
$$F^{\text{T}}_{\text{nonind}(A, \psi)}(U, T, \langle a, b \rangle) = F^{\text{T}}_{\psi(a)}(U, T, b) : D$$

Inductive Argument

- For an inductive argument we need to know
 - The set *A*, over which the argument is indexed over.
 - $A = \{*\}$ give the special case of a single argument.
 - Depending on the result of T applied to the arguments of A, i.e. depending on $A \rightarrow D$, the later arguments of the constructor: We need a function $\psi : (A \rightarrow D) \rightarrow OP_D$.

$$\frac{A: \text{Set} \quad \psi: (A \to D) \to \text{OP}_D}{\text{ind}(A, \psi): \text{OP}_D}$$

$$F^{U}_{ind(A,\psi)}(U,T) = (a:A \to U) \times F^{U}_{\psi(T \circ a)}(U,T) : Set$$

$$\mathbf{F}_{\mathrm{ind}(A,\psi)}^{\mathrm{T}}(U,T,\langle a,b\rangle) = \mathbf{F}_{\psi(T\circ a)}^{\mathrm{T}}(U,T,b):D$$

Examples

- If $\psi, \psi' : OP_D$, let $\psi +_{OP} \psi'$ be the code for the ind.-rec. definitions with the constructors of ψ and ψ' coded into one constructor.
- Ordinary inductive definitions correspond to elements of $\operatorname{OP}_{\{*\}}$.
 - Then $T_{\gamma} : U_{\gamma} \to \{*\}$ is trivial.
- Code for \mathbb{N} is

```
\operatorname{init}(*)
+OPind({*}, \lambda x.\operatorname{init}(*)) : OP<sub>{*}</sub>
```

Examples

• Code for A + B is

nonind($A, \lambda x.init(*)$) +OPnonind($B, \lambda x.init(*)$) : OP_{*}

• Code for W(A, B) is

nonind(A, λx .ind(B(x), λy .init(*))) : OP_{*}

• Code for a universe closed under \mathbb{N} , Σ is

 $init(\mathbb{N}) +_{OP} ind(\{*\}, \lambda A.ind(A(*), \lambda B.init(\Sigma(A(*), B))))$: OP_{Set}

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4. Results

- Generalisation to indexed inductive-recursive definitions has been developed.
 - Corresponds to the simultaneous ind.-rec. definitions of several sets $U_{\gamma}(i)$: Set (i : I), together with $T_{\gamma}(i) : U_{\gamma}(i) \to D[i]$.
- Special case: identity type.

Applications in Generic Programm.

- Generic (or better generative) programming is the definition of functions, which depend on the structure of types.
 - More than just simple polymorphism, in which one forms a type from another type without looking into it.
- Generic programming is used in C + + where one can define typelists and functions by induction over type lists.
- Similarly, in generic Haskell one defines functions by induction over the definition of data types.
- Goal is highly generic programs, automated software production.

OP_D and Generic Programming

- OP_D is a very general data type of types.
 Allows to define functions which take
 - an element of $\gamma : \operatorname{OP}_D$,
 - \checkmark and an element of U_{γ} ,
- and compute
 - a new element $\gamma' : OP_D$
 - and a new element of $U_{\gamma'}$.
- A very general form of generic programming.
- One example is the embedding of an inductive type into the same inductive type, but extended by one more constructor.
 - Not possible to treat this using ordinary polymorphism.

OP_D and Generic Programming

- Marcin Benke, Patrik Jansson and Peter Dybjer have used weak versions of OP_D in generic programming.
- One example is the type of finitary inductive definitions (inductive argument not indexed over sets).
- They were able to
 - define a generic decidable equality for such sets,
 - and show that it is an equivalence relation.

Related Structures

- In order to define models of type theory (or other theories) inside type theory, one often needs to define
 - **• a** U : Set

• together with sets $\mathrm{T}:\mathrm{U}\to\mathrm{Set}$ simultaneously inductively.

- So T(x) is not fixed but defined inductively by referring to the inductive definition of U and other sets T(y).
- Therefore we cannot refer to T(x) negatively as in

$$\widehat{\Sigma}: (x: \mathbf{U}) \to (\mathbf{T}(x) \to \mathbf{U}) \to \mathbf{U}$$

Example

For instance one defines simultaneously inductively

Types : Set
Terms : Types
$$\rightarrow$$
 Set

with constructors like

ap :
$$(A, B : \text{Types})$$

 $\rightarrow \text{Terms}(A \widehat{\rightarrow} B)$
 $\rightarrow \text{Terms}(A)$
 $\rightarrow \text{Terms}(B)$

(More precisely additional dependency on contexts needed).

Conclusion

- Introduction into dependent type theory (Martin-Löf Type Theory).
- Ind-rec. definitions as a generalisation of the underlying principles.
- Introduction of a type theory of ind.-rec. definitions.
- Contains a data type OP_D of codes for ind.-rec. definitions.
- Proof-theoretic strength known to be in [|KPM|, |KPM⁺|].
- Applications in generic programming.

Future Research

- Integration of Mahlo principle ("Mahlo-inductive-rec. definitions").
- Combination with coalgebras (couniverses).
- Integration of extended principles like the one just mentioned.
- More examples for usage of truly inductive-recursive definitions in programming.
 - Only known non-universe examples are:
 - Modelling of partial functions in type theory.
 - Normalisation proof of Martin-Löf type theory.
 - Expected that there are many more applications.
- More applications in generic/generative programming.